DOSING ROBOTS Automated dispensing solutions

DOSING ROBOT

ADVANTAGES	BENEFITS
System in accordance with the European Directive 2006/42 / EC	Accurate and repeatable dispensing
Integrated control systems and metering	Higher production yield
Rigid structure	Precision and reliability guarantee
Interface production line	Economic automation
Emergency stop and reset	High quantity treatment process
Camera option	Frees operators for other tasks
Different communication modes	Integrated and autonomous system



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PRESENTATION ·····

With its integration partner MA Systeme (since 2009), PDS has a complete and efficient expertise on dosing robot solutions ready for use.

Robots Janome offer a competitive advantage by increasing the quality and productivity of their manufacturing process. By providing you with these high performance devices, PDS put the costs reduction as priority with a range of new generation robots that eliminate expensive automation and reduce human intervention. Innovative and versatile manufacturer, Janome produced patented industrial equipment since 20 years.

The robots can be used in many sectors: electronics, automotive, aerospace, medical or cosmetic.

Associated with the appropriate application system, they can perform several types of applications: points, lines, potting, dam & filling, underfilling, encapsulation, coating, jetting etc.

Cartesian robot

These tables available in version 3 or 4 axes have displacement capacities ranging from 200 to 600 mm. Mainly used for dispensing, screwing and grip, they are very accurate.

Scara robot

They have an action field of 250 to 550 mm and a working area of 650 to 1000 mm. The weight carried by the Z axe is from 4 to 20 kg. Welding applications, gluing and displacement are suitable for these types of robots. Their CPU has 37E and 40S to handle related functions.

CARTESIAN ROBOTS : JRN SERIES



CARTESIAN ROBOTS					
PART NUMBER	AXE X, Y	AXE Z	AXE R		
JR3203N	200 x 200 mm	50 mm			
JR3204N	200 x 200 mm	50 mm	±360°		
JR3303N	300 x 320 mm	100 mm			
JR3304N	300 x 320 mm	100 mm	±360°		
JR3403	400 x 400 mm	150 mm			
JR3404N	400 x 400 mm	150 mm	±360°		
JR3503N	510 x 510 mm	150 mm			
JR3504N	510 x 510 mm	150 mm	±360°		
JR3603N	510 x 620 mm	150 mm			
JR3604	510 x 620 mm	150 mm	±360°		

Points - Lines - Potting - Dam & Filling - Underfilling - Encapsulation - Sealing - Coating - Jetting

PRESENTATION

PDS offers a complete range of dosing robots to respond to your more specific demands in terms of positioning and dispensing. These dosing robots operate with syringes and valve systems, to a working area from 200 mm x 200 mm to 510 mm x 620 mm. So these robots are the ideal solution for optimizing precision works and reducing production costs.

Designed to be easy to program, a software has been specifically created to make the handling of the device accessible by avoiding the use of a complex programming language. In addition, the interface is programmable via a control unit or PC (Dispensing software included).

The Cartesian robot tables have robust and reliable units in aluminum ensuring the rigidity whatever operation is performed.

They offer a wide range of work areas for a small obstruction. These devices are ideal for autonomous operations and can easily be integrated on automated assembly lines.

- Optical encoders of displacement control
- Auto shutdown in case of error detection
 - No time wasted and maximization of the productivity
 - Heavy-duty aluminum structure

- Memory capacity : 30 000 points or 255 programs
- Modular RS232 C interface to connect to a PC, RS-422 port for learning case and I / O system

SPECIFICATIONS		JR 3203N	JR 3204N	
	Х	200 mm	200 mm	
A	Y	200 mm	200 mm	
Axes	Z	50 mm	50 mm	
	R		±360°	
	PTP (X,Y)	5-550 mm/sec	5-550 mm/sec	
Greed	PTP (Z)	2,5-250 mm/sec	2,5-250 mm/sec	
Speeu	PTP (R)		6-600°/sec	
	CP (X,Y,Z)	0,1-500 mm/sec	0,1-500 mm/sec	
	Axe X, Y	±0,01 mm	±0,01 mm	
Accuracy of repeatability	Axe Z	±0,01 mm	±0,01 mm	
	Axe R		±0,02°	
Waight load	Piece	7kg	7kg	
vvelgrit loau	Tool	3,5kg	3,5kg	
Acceptable Ine	ertia Moment			
Learning meth	od	Distance Learning (JOG) or manual data input (MDI)		
Learning Syste	em	JR C-Points software designed for the user via the I $/$ O		
Interpolation fu	unction	Three-dimensional interpolation of lines and arcs		
Training Syste	m	Stepper motor / 5 phases		
Control system	n	PTP and CP		
Number of axis	S	3	4	
External interfa	ace	RS 232C 1 channel for PC, 2 channels for external device optional RS422 box only for learning		
External I / O		I / O-SYS Input: 16 / Output:	16-input: 5 / output 7 are free	
PLC function		/ 0-1 - Input: 8 / Output: 8	3 (4 relay contacts) - all free	
Capacity progr	rams	100 programs (100	0 steps / 1 program)	
Memory Capa	city	255 pr	ograms	
Dimensions (V	V x D x H]	320 x 377 x 536 mm	320 x 377 x 655 mm	
Weight		18 kg	18 kg	
Power Source		CA 180-250 V. 50 Hz. 200 VA		

CA 180-250 V, 50 Hz, 200 VA

CARTESIAN ROBOT : JR3200N



PRESENTATION

The JR3200N model is the first representative of a large series of innovative cartesian robots. With a size of only 320 x 387,5mm, the device is very compact. Like all models in these series, it is easy to program the system by using the software.

Cartesian dosing robots provided by PDS are used to interpolate lines and curves automatically in all axes. The JR3204N version is equipped with a fourth axis of rotation for 3D movement. The programming software, easy to use, allows you to create programs quickly thanks to its support system. Within a few minutes, the device is ready for use. The system is equipped with an I / O signal interface (16 x inputs / 16 x outputs) to allow you to control external systems.

CARTESIAN ROBOT : JR3300N



The robot JR3300N series is the most popular of the range of robotic tables. The Cartesian dosing robot has a working area of 300 x 320 mm.

Cartesian dosing robots provided by PDS are used to interpolate lines and curves automatically in all axes. The JR3304N version is equipped with a fourth axis of rotation for 3D movement.

The programming software, easy to use, allows you to create programs quickly thanks to its support system. Within a few minutes, the device is ready for use. The system is equipped with a signal interface I / S (16 x inputs / 16 x outputs) to allow you to control external systems.

SPECIFICATIONS		JR 3303N	JR 3304N	
	Х	300 mm	300 mm	
A	Υ	320 mm	320 mm	
Axes	Z	100 mm	100 mm	
	R		±360°	
	PTP (X,Y)	8-800 mm/sec	8-800 mm/sec	
Speed	PTP (Z)	3,2-320 mm/sec	3,2 - 320 mm/ sec	
opeeu	PTP (R)		8-800°/sec	
	CP (X,Y,Z)	0,1-800 mm/sec	0,1-800 mm/sec	
A	Axe X, Y	±0,01 mm	±0,01 mm	
Accuracy of repeatability	Axe Z	±0,01 mm	±0,01 mm	
	Axe R		±0,02°	
\//eight load	Piece	11kg	11kg	
vveigint ibau	Tool	6kg	6kg	
Acceptable Ine	ertia Moment		90 kg . Cm²	
Learning meth	od	Distance Learning (JOG) or manual data input (MDI)		
Learning Syste	m	JR C-Points software designed for the user via the I $/$ O		
Interpolation fu	Inction	Three-dimensional interpolation of lines and arcs		
Training Syster	m	Stepper motor / 5 phases		
Control system	ı	PTP and CP		
Number of axis	6	3 4		
External interfa	ace	RS 232C 1 channel for PC, 2 channels for external device optional RS422 box only for learning		
External I / O		I / O-SYS Input: 16 / Output: '	16-input: 5 / output 7 are free	
PLC function		/ 0-1 - Input: 8 / Output: 8	3 (4 relay contacts) - all free	
Capacity progr	rams	100 programs (1000	D steps / 1 program]	
Memory Capac	city	255 pr	ograms	
Dimensions (W	V x D x H)	560 x 529 x 649 mm	560 x 529 x 840 mm	
Weight		35 kg	35 kg	
Power Source		CA 180-250 V, 50 Hz, 200 VA		

SPECIFI	CATIONS	JR 3403N	JR 3404N	
	Х	400 mm	400 mm	
A	Y	400 mm	400 mm	
AXES	Z	150 mm	150 mm	
	R		±360°	
	PTP (X,Y)	8-800 mm/sec	8-800 mm/sec	
Speed	PTP (Z)	3,2-320 mm/sec	3,2-320 mm/sec	
opeeu	PTP (R)		8-800°/sec	
	CP (X,Y,Z)	0,1-800 mm/sec	0,1-800 mm/sec	
	Axe X, Y	±0,01 mm	±0,01 mm	
Accuracy of repeatability	Axe Z	±0,01 mm	±0,01 mm	
	Axe R		±0,02°	
Maight load	Piece	11kg	11kg	
vvelgi it loau	Tool	6kg	6kg	
Acceptable Ine	ertia Moment		90 kg . Cm²	
Learning meth	od	Distance Learning (JOG) or manual data input (MDI)		
Learning Syste	em	JR C-Points software designed for the user via the I $/$ O		
Tnterpolation f	unction	Three-dimensional interpolation of lines and arcs		
Training Syste	m	Stepper motor / 5 phases		
Control system	ı	PTP and CP		
Number of axis	6	3	4	
External interfa	ace	RS 232C 1 channel for PC, 2 channels for external device optional RS422 box only for learning		
External I / O		I / O-SYS Input: 16 / Output:	16-input: 5 / output 7 are free	
PLC function		l / 0-1 - Input: 8 / Output: 8	8 (4 relay contacts) - all free	
Capacity progr	rams	100 programs (100	0 steps / 1 program]	
Memory Capa	city	255 pr	rograms	
Dimensions (V	V x D x H]	584 x 629 x 799 mm	584 x 629 x 890 mm	
Weight		42 kg	42 kg	
Power Source		CA 180-250 V, 50 Hz, 200 VA		

CA 180-250 V, 50 Hz, 200 VA

CARTESIAN ROBOT : JR3400N



With its large working area of 400 x 400 mm, the JR3400N dispensing robot takes less than 629 mm² workspace. This robot has an opening on the side for easy handling unhardy objects in and around the work area.

Cartesian dosing robots provided by PDS are used to interpolate lines and curves automatically in all axes. The JR3404N version is equipped with a fourth axis of rotation for 3D movement.

The easy-to-use software program allows you to create programs quickly thanks to its support system. Within minutes, the device is ready for use. The system is equipped with an I / O signal interface [16 x inputs / 16 x outputs] to allow you to control external systems.

CARTESIAN ROBOT : JR3500N



Offering a wide working area of 510×510 mm, the robot JR3500N dosing yet takes less than 727 mm² workspace. The JR3500N robot has an opening on the side for easy handling unhardy objects in and around the work area

Cartesian dosing robots provided by PDS are used to interpolate lines and curves automatically in all axes. The JR3504N version is equipped with a fourth axis of rotation for 3D movement.

The easy-to-use programming software allows you to create programs quickly thanks to its support system. Within a few minutes, the device is ready for use. The system is equipped with an I / O signal interface (16 x inputs / 16 x outputs) to allow you to control external systems.

SPECIFICATIONS		JR 3503N	JR 3504N	
	Х	510 mm	510 mm	
Avec	Y	510 mm	510 mm	
AXES	Z	150 mm	150 mm	
	R		±360°	
	PTP (X,Y)	8-800 mm/sec	8-800 mm/sec	
Speed	PTP (Z)	3,2-320 mm/sec	3,2-320 mm/sec	
Speed	PTP (R)		8-800°/sec	
	CP (X,Y,Z)	0,1-800 mm/sec	0,1-800 mm/sec	
	Axe X, Y	±0,01 mm	±0,01 mm	
Accuracy of repeatability	Axe Z	±0,01 mm	±0,01 mm	
	Axe R		±0,02°	
Maight load	Piece	11kg	11kg	
vvelgi it load	Tool	6kg	6kg	
Acceptable Ine	ertia Moment		90 kg . Cm²	
Learning meth	nod	Distance Learning (JOG) or manual data input (MDI)		
Learning Syste	em	JR C-Points software designed for the user via the I $ angle$ O		
Tnterpolation	function	Three-dimensional interpolation of lines and arcs		
Training Syste	m	Stepper motor / 5 phases		
Control system	n	PTP and CP		
Number of axi	S	3	4	
External interf	ace	RS 232C 1 channel for PC, 2 channels for external device optional RS422 box only for learning		
External I / O		I / O-SYS Input: 16 / Output: 1	16-input: 5 / output 7 are free	
PLC function		/ 0-1 - Input: 8 / Output: 8	3 (4 relay contacts) - all free	
Capacity prog	rams	100 programs (100	0 steps / 1 program)	
Memory Capa	city	255 pr	ograms	
Dimensions (V	V x D x H]	676 x 728 x 799 mm	676 x 728 x 890 mm	
Weight		43 kg	43 kg	
Power Source		CA 180-250 V, 50 Hz, 200 VA		

SPECIFICATIONS		JR 3603N	JR 3604N	
	Х	510 mm	510 mm	
A	Y	620 mm	620 mm	
Axes	Z	150 mm	150 mm	
	R		±360°	
	PTP (X,Y)	8-800 mm/sec	8-800 mm/sec	
Speed	PTP (Z)	3,2-320 mm/sec	3,2-320 mm/sec	
Speed	PTP (R)		8-800°/sec	
	CP (X,Y,Z)	0,1-800 mm/sec	0,1-800 mm/sec	
	Axe X, Y	±0,01 mm	±0,01 mm	
Accuracy of repeatability	Axe Z	±0,01 mm	±0,01 mm	
· - [,	Axe R		±0,02°	
Weight load	Piece	11kg	11kg	
vvelgitt load	Tool	6kg	6kg	
Acceptable Ine	ertia Moment		90 kg . Cm²	
Learning meth	od	Distance Learning (JOG) or manual data input (MDI)		
Learning Syste	em	JR C-Points software designed for the user via the I $/$ O		
Tnterpolation f	unction	Three-dimensional interpolation of lines and arcs		
Training Syste	m	Stepper motor / 5 phases		
Control system	ı	PTP and CP		
Number of axis	5	3 4		
External interfa	асе	RS 232C 1 channel for PC, 2 channels for external device optional RS422 box only for learning		
External I / O		I / O-SYS Input: 16 / Output:	16-input: 5 / output 7 are free	
PLC function		/ 0-1 - Input: 8 / Output: 8	8 (4 relay contacts) - all free	
Capacity progr	rams	100 programs (100	0 steps / 1 program]	
Memory Capa	city	255 pr	rograms	
Dimensions (V	V x D x H]	788 x 731 x 800 mm	788 x 731 x 800 mm	
Weight		44 kg	44 kg	

Power Source

CA 180-250 V, 50 Hz, 200 VA

CARTESIAN ROBOT : JR3600N



With its large working area of 620 x 510 mm, the JR3600N dispensing robot takes less than 787 mm² workspace. The JR3600N robot has an opening on the side for easy handling unhardy objects in and around the work area.

Cartesian dosing robots provided by PDS are used to interpolate lines and curves automatically in all axes. The JR3604N version is equipped with a fourth axis of rotation for a 3D displacement.

The programming software, easy to use, allows you to create programs quickly thanks to its support system. Within few minutes, the device is ready for use. The system is equipped with an I / O signal interface (16 x inputs / 16 x outputs) to allow you to control external systems.

CARTESIAN ROBOT : JR3000NE (ENCODER)



PRESENTATION

Dosing robot JRNE series, sister of JRN series, is a Cartesian robot equipped with an encoder, allowing feedback on the actual position.

This ensures an even more precise positioning.

5 different model ranges are available, with an operating size from 200x200mm to 510x510mm.

These robots work with dispensing syringes and valve systems and is the best way to optimize your most sensibles precision works. Equipped with the same programming software as the JRN series, the JRNE series is just as intuititive and easy to program as the JRN serie.

- Rigid structure : extruded aluminum column, base in aluminum molded under pressure
- Mechanism labyrinth : Prevents intrusion of foreign objects under the work table
- Smooth movement : microstepped control system

- Simple learning : Software «JRC-Points» allowing the user to easily figure out the robot or to create original programs
- Embedded optical encoders continuously control the axis movement and automatically stop the operation by detecting position errors
 - Simple Sequencer : single sequencer functions are built independently, allows up to 1000 steps

JR3000NE SERIE : SPECIFICATIONS

SPECIFICATIONS		3 AXES (SYNCHRONOUS CONTROL)				4 AXES (SYNCHRONOUS CONTROL)			
		JR3203NE	JR3303NE	JR3403NE	JR3503NE	JR3204NE	JR3303NE	JR3404NE	JR3504NE
	Х	200	300	400	510	200	300	400	510
Axes	Υ	200	320	400	510	200	320	400	510
	Z	50	100	150	150	50	100	150	150
	R (degrees)					±360	±360	±360	±360
	Piece (kg)	7	11	11	11	7	11	11	11
vegneload	Tool (kg)	3,5	6	6	6	3,5	6	6	6
	Axe X Y (mm/sec)	700 (7-700)	800 (8-800)	800 (8-800)	800 (8-800)	700 (7-700)	800 (8-800)	800 (8-800)	800 (8-800)
Speed (max) PTP	Axe Z (mm/sec)	250 (2,5-250)	320 (3,2-320)	320 (3,2-320)	320 (3,2-320)	250 (2,5-250)	320 (3,2-320)	320 (3,2-320)	320 (3,2-320)
	Axe R (degré/sec)					600 (6-800)	800 (8-800)	800 (8-800)	800 (8-800)
Speed (max) CP	Axes X,Y,Z combined (mm/ sec)	500 (0,1-500)	800 (0,1-800)	800 (0,1-800)	800 (0,1-800)	500 (0,1-500)	800 (0,1-800)	800 (0,1-800)	800 (0,1-800)
	Width	320	560	584	676	320	560	584	676
Dimensions	Depth	387	529	629	728	387	529	629	728
	Height	540	649	799	799	655	840	890	890
Robot weight (k	g)	18	35	42	43	18	35	42	43
Power Source		CA 90 - 132 V / CA 180 - 250 V							
Output		200 W							
Learning System				Points JR-C	C programming des	signed for the user	via the I / O		
Learning method				Direct input via tea	ach pendant (optio	nal). Offline - Learni	ng via PC (optional]	
Capacity progra	ims				255 pr	rograms			
Storage capacit	Σ y				30,00	0 items			
Languages		English / German / French / Spanish / Italian / Chinese / Japanese							

SCARA ROBOT : JS SERIE



SPECIFICATIONS		JS250	JS350	JS450	JS550
Acceptab	le Inertia		0.1 k	g. M²	
Detection	position		Absolute	encoder	
Control system		PTP comm	PTP command (point to point). CP control (continuous path)		
Interpolation function		Three-dimensional interpolation of lines and arcs			
Learning method		Direct learning $ earrow Distance Learning (JOG) earrow Manual Data Entry (MDI)$			
External	E/S	/ O - SYS Input: 15 / Output: 14 - all covered / O - 1 - input: 18 output: 22 (4 relay contacts) - all free Optional I / O - H Input: 4 / Output: 4 (2 relay contacts) - all fre		ered i) - all free acts) - all free	
series	RS232C	1 channel for PC (COM1), 2 channels	s for external device	es (Com 2 COM 3)
	Locking		Reverse L	ock Signal	

PRESENTATION

The Scara robot (Selective Compliance Assembly Robotic Arm) proposed by PDS is the ideal answer to your automation on assembly line needs. They bring you the flexibility to work either as stand-alone systems or as key components of an automated dispensing solution.

It consists of an articulated arm mounted on a vertical axis, which allows to cover a very large area of work and make rapid and accurate movements. Versatile and compact, it is easy to program and integrate into a production line.

JS series uses an exclusive Janome bearing configuration

coupled with AC servomotors to allow high movement speed and optimum precision.

Integrated in automation, it offers the ability to control a variety of external equipment and communicate with complex controllers.

I / O preconfigured connections allow an easy integration of a syringe or a dispensing valve system while the built-in sequencer simplifies installation of a dosing arm on online transfer systems, rotary tables or pallets assembly lines.

- Increased precision thanks to double-shaft mechanism
- Memory up to 255 programs or 30 000 points
- Speed standard cycle time: 0.4 seconds on average
- Maximum speed: 6,300 mm / Sec7
- Programming method JR C-Points software, easy to use
- Digital imaging in option
- Automatically detect and correct height, ideal for

dispensing

SCARA ROBOT: JS SERIE

SPECIFICATIONS		JS250	JS350	JS450	JS550	
A	xes		4 (synchror	nous control)		
	Arm J1	100 mm	125 mm	225 mm	325 mm	
Arm length	Arm J2	150 mm	225 mm	225 mm	225 mm	
	Arm J1 et J2	250 mm	350 mm	450 mm	550 mm	
Operating range form)	(in a X Y square	206 mm	210 mm	306 mm	349 mm	
	Arm J1	±130°	±130°	±130°	±130°	
Onenetine recent	Arm J2	±145°	±150°	±145°	±150°	
Operating range	Axe Z	150 mm°	150 mm°	150 mm°	150 mm°	
	Axe R	±360°	±360°	±360°	±360°	
Portable maximum weight		4kg	6kg 6kg		6kg	
	J1 and J2	4.200 mm/sec	6.300 mm/sec	5.600 mm/sec	6.200 mm/sec	
Top speed	Axe Z	1.400 mm/sec	1.850 mm/sec	1.850 mm/sec	1.850 mm/sec	
	Axe R	1.750 °/sec	1.900 °/sec	1.900 °/sec	1.900 °/sec	
	Axe X and Y	± 0.01 mm	± 0.01 mm	± 0.015 mm	± 0.015 mm	
Accuracy of repeatability	Axe Z	± 0.01 mm	± 0.01 mm	± 0.01 mm	± 0.01 mm	
repeatability	Axe R	± 0,01 °	± 0,01 °	± 0,01 °	± 0,01 °	
Standard cycle ti	me	0.39 sec (1kg)	0.38 sec (1kg)	0.39 sec (1kg)	0.41 sec (1kg)	
Simple sequence	r	100 programs				
Aberrante detec	tion		Auto function	n - Diagnostic		
Installed alimenta	ation		AC 180-250 V	(single phase)		
Installed power		950 VA		1.050 VA		
Temperature			0 to 40 ° C, 20-95% relativ	e humidity (non-condensing)		
Weight		27 kg	28 kg	28 kg	29 kg	
Control box weight			20	kg		

Control box weight

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SCARA ROBOT : JS SERIE



SPECIFICATIONS		JS650	JS750	JS880	JS1000
Acceptable in	iertia moment		0.2 k	g. M²	
Detection	n position		Absolute	encoder	
Control	system	PTP comm	and (point to point)	. CP control (contir	nuous path)
Interpolati	on function	Three	e-dimensional interp	oolation of lines and	arcs
Learning method		Direct learning / Distance Learning (JOG) / Manual Data Entry (MDI)			
Learning System		Janome Software: JR - R Points			
Programming capability		255 programs or 30000 points			
External	E/S	/ 0 / 0 - 1 - Optional / 0) - SYS Input: 15 / (input: 18 output: 2) - H Input: 4 / Outp	Output: 14 - all cov 2 (4 relay contacts put: 4 (2 relay cont	ered 6) - all free acts) - all free
series	RS232C	1 channel for PC (COM1), 2 channels	for external device	es (Com 2 COM 3)
	Lock		Reverse L	ock Signal	
Wiring and pip	bes		14 cables for sig	jnals, 4 air ducts	

PRESENTATION

Easy to program and to implement in the production chain, the multi-axis dispensing robot Scara proposed by PDS is ideal for use with conveyors or for heavy or bulky products.

Although it offers a small obstruction space with its «all-in-one» compact structure and integrated control unit, the materials it is made by allow it to be rigid and strong in order to be able to exploit effectively your heaviest materials.

Its flexible interface allows you to easily program your specific operations with expanded memory up to 255 programs and 30,000 points recorded. It is accessible and easy to learn even without major knowledge in computer science.

- A unique software avoids the use of a complex programming language
- Programmable interface via a control unit or a PC
- Compact size and built-in sequencer allows easy integration of automated assembly lines
- Robust and reliable units

- Ideal for operations in autonomous and automated mode
- Possibility of making samples before buying the product

SCARA ROBOT : JS SERIE

SPECIFICATIONS		JS650 JS750		JS880	JS1000	
Axes		4 (synchronous control)				
	Arm J1	300 mm	400 mm	400 mm	520 mm	
Arm length	Arm J2	350 mm	350 mm	480 mm	480 mm	
	Arm J1 et J2	650 mm	750 mm	880 mm	1000 mm	
Operating range (in the form of XY square)		436 mm	505 mm	602 mm	748 mm	
	Arm J1	±130°	±130°	±130°	±130°	
Openating paper	Arm J2	±150°	±150°	±160°	±160°	
Operating range	Axe Z	200 mm°	200 mm°	200 mm°	200 mm°	
	Axe R	±360°	±360°	±360°	±360°	
Portable maximu	m weight	20 kg	20 kg	20 kg	20 kg	
	J1 and J2	6.700 mm/sec	7.200 mm/sec	6.500 mm/sec	7.000 mm/sec	
Top speed	Axe Z	2000 mm/sec	2000 mm/sec	2000 mm/sec	2000 mm/sec	
	Axe R	1.800 °/sec	1.800 °/sec	1.800 °/sec	1.800 °/sec	
	Axe X and Y	± 0.02 mm	± 0.02 mm	± 0.025 mm	± 0.025 mm	
Accuracy of	Axe Z	± 0.01 mm	± 0.01 mm	± 0.01 mm	± 0.01 mm	
repeated may	Axe R	± 0,01 °	± 0,01 °	± 0,01 °	± 0,01 °	
Standard cycle Ti	me	0.44 sec (1kg)	0.46 sec (1kg)	0.47 sec (1kg)	0.50 sec (1kg)	
Simple sequence	-	100 programs				
Aberrante detect	ion	Auto function - Diagnostic				
Installed alimenta	tion		CA 180	- 250 V		
Installed power			1.90	O VA		
Weight Robot		65 kg	67 kg	68 kg	70 kg	
Weight Control u	nit	27 kg				

SCARA ROBOT : JSR



PRESENTATION

Accurate and easy to use, the Scara robot motor stepper JSR4400N series offers a convenient and inexpensive way to automate your workflow. Its innovative technology ensures a smooth and precise movement. Also meet the environmental standards, it is designed to maintain extremely low power levels. Featuring an intuitive and accessible teaching method, it allows you to save considerable time savings by programming the device.

Applications :

- Dispensing
- Pick-Up
- Assembly
- Palletization
- Removing
- Welding

	SPECIFICATIONS		JSR44U3N	JSR44U4N
	Axe		3	4
	Arm length	Arm J1	260 mm	260 mm
		Arm J2	180 mm	180 mm
		Arm J1 and J2	440 mm	440 mm
	Operating range	Arm J1	±90°	±90°
		Arm J2	±150°	±150°
		Axe Z	100 mm	100 mm
		Axe R	±360°	±360°
	Top speed	J1 and J2	1500 mm/sec (1kg load)	1500 mm/sec
			1400 mm/sec (3kg load)	1400 mm/sec
			1300 mm/sec (5 kg load)	1300 mm/sec
		Axe Z	320 mm/sec	320 mm/sec
		Axe R		900°/sec
	Accuracy of repeatability	Axe X and Y	±0,02 mm	±0,02 mm
		Axe Z	±0,01 mm	±0,01 mm
		Axe R		±0,02 mm
	Learning method		Direct Learning, Distance Learning (JOG), manual data input (MDI)	
	Training System		Stepping motor in 5 steps (controlled by encoder)	
	Control system		PTP command (point to point), continuous path control (PC)	
	Interpolation function		3D linear interpolation and bows	
	External interface		RS232C 3 Channels for external control box + PC	
	I / O External		l / O-SYS Input: 16 / Output: 16-Input 2 / Output: 6 free I / O-1 - Input: 8 / Output: 8 (4 relay contacts) - available	
	Programming capability		255 Programs	
	Storage capacity		30,000 points or 255 programs	
	CPU		32 Bits	
	Dimensions (W x D x H)		880 x 773 x 840 mm	880 x 858 x 840 mm
	We	ight	41 kg	41 kg

Weight

Power supply

APPLICATIONS

ELECTRONICS

- Coating for printed circuits
- Distribution glue for mobile device circuit
- Distribution paste for control circuit
- Clamping screw
- UV glue dispensing
- Pick and place small parts

CARS

MEDICAL

- Spray
- Pick and place fuse box
- Epoxy resin deposited by car relay
- Sealing for vehicle lighting part
- Joint casting for the engine
- Lubrication of air conditioner parts



- Fill solutions
- Many heads of dispensing system
- Weight management system



OTHERS

- Ink application on spoons, glasses
- Removal of red ink in the database
- Fill molds with chocolate
- Cans fill with syrup







TO ORDER, PLEASE CALL +33 (0)1 39 62 40 92

Poly Dispensing Systems

FRANCE 122, Chemin de la Cavée 78630 ORGEVAL Tel : 01 39 62 40 92 Fax : 01 39 62 40 94 Mail : contact@polydispensing.com

The fluid dispensing being the cornerstone of numerous production chains, PDS emphasis on this specific need by proposing a wide range of innovative and efficient dispensing equipments.

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Persuaded that our expertise must be complete, we also supply you tools in order to prepare your fluid (mixture and degassing) and polymerize your glues (UV sunstroke). Our range of consumables (needles, syringes, static mixers etc are also considered as the best in the market.

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